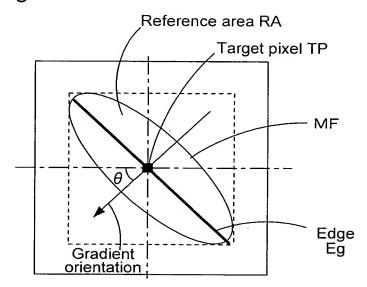
Fig.1



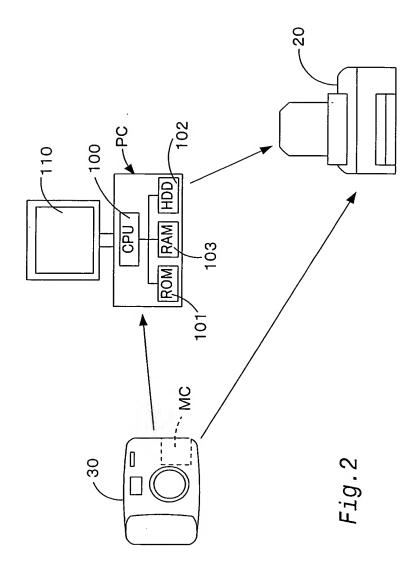


Fig.3

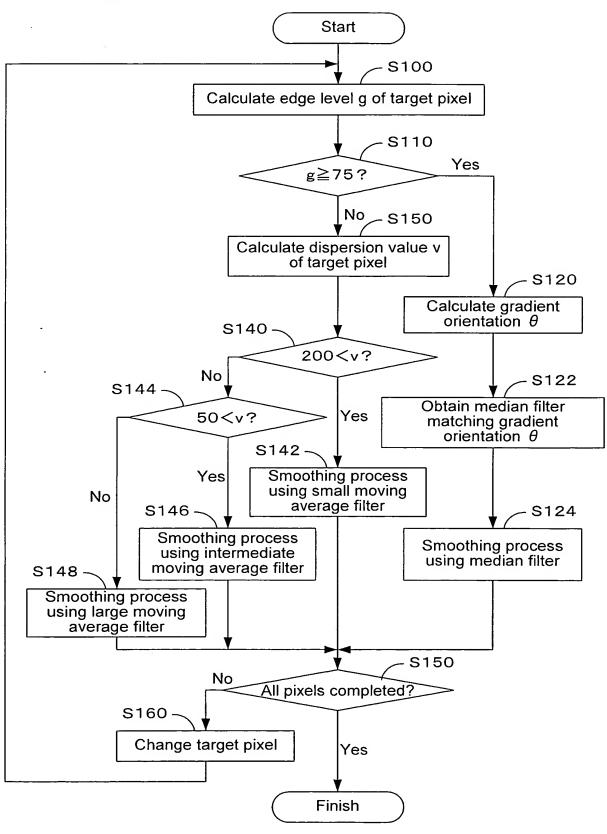


Fig.4(a)

Δfx						
-1	0	1				
-1	0	1				
-1	0	1				

Fig.4(b)

Δfy						
1	1	1				
0	0	0				
-1	-1	-1				

Fig.5(a)

Fig.5(b)

△ fy					
1	0	1	0	1	
0	0	0	0	0	
0	0	0	0	0	
0	0	0	0	0	
-1	0	-1	, 0	-1	

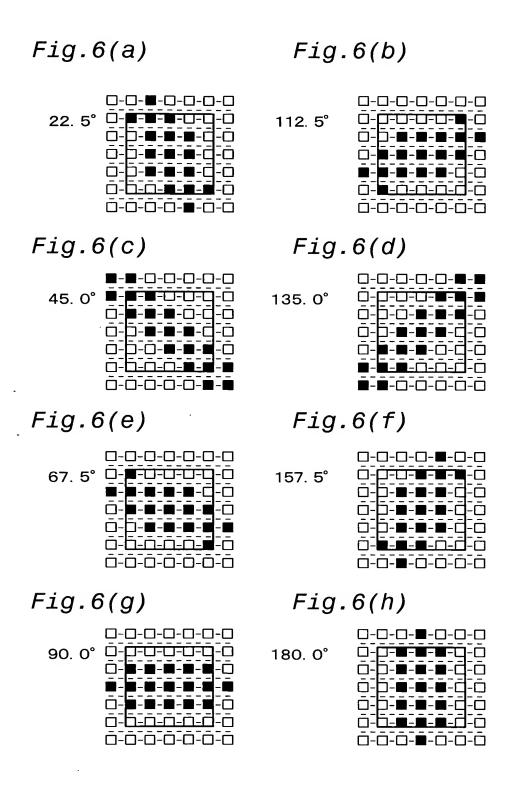


Fig.7

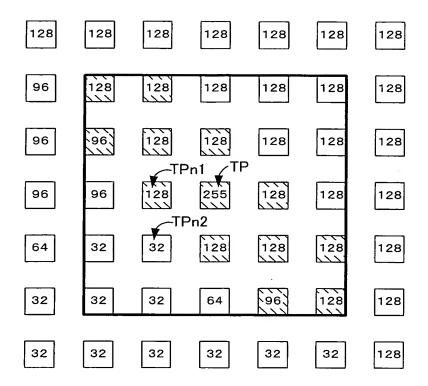


Fig.8

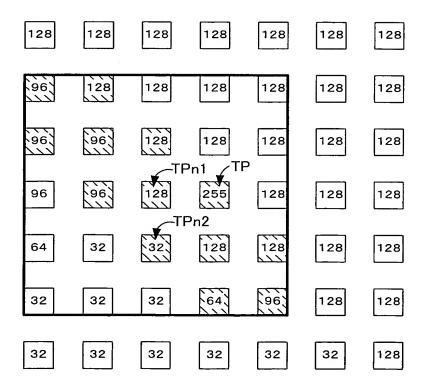


Fig.9

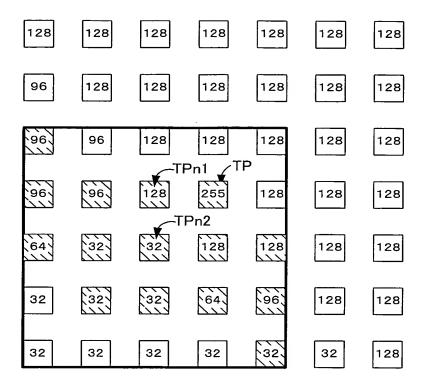


Fig. 10

Target Pixel	Processed pixel value in embodiment	Processed pixel value in conventional example	Gradient orientation $ heta$
TP	128	111	51°
TPn1	128	101	56°
TPn2	96	83	69°

Fig.11

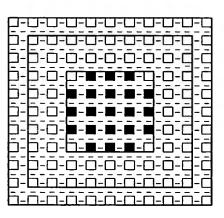


Fig.12

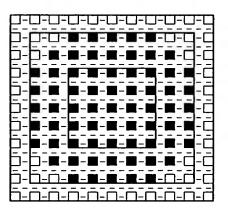


Fig.13

